The Use of On-Demand Forecasts for Weather Optimization of Aircraft Tracks

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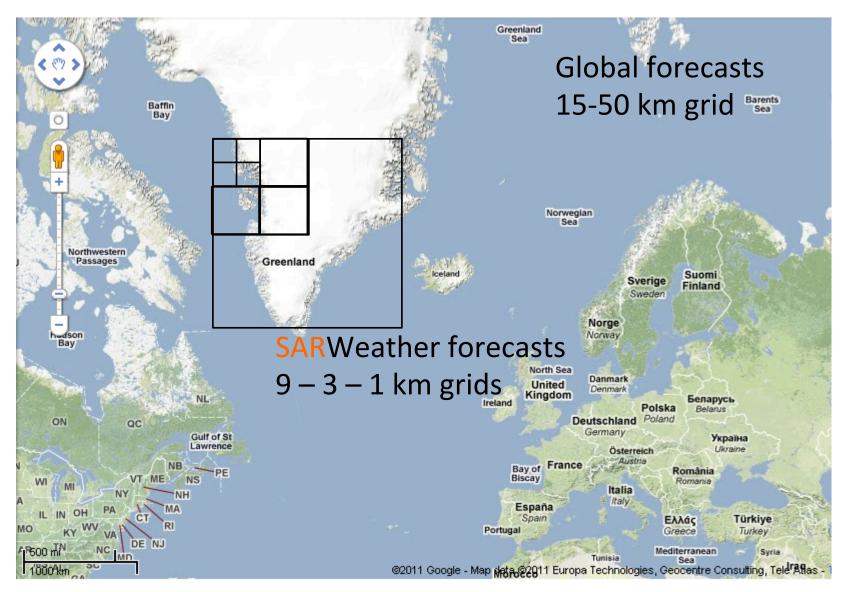


Overview

- Numerical Weather Models
 - Importance of resolution
- Routing optimization using NWM
- Current Crisis Response System
 - SARWeather general description
- Use of observations from UAS's
- On-going research
- Conclusions



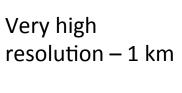
Importance of high resolution

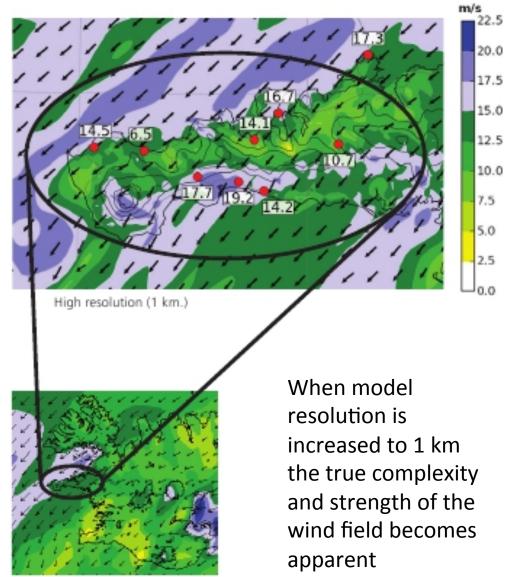






Importance of high resolution



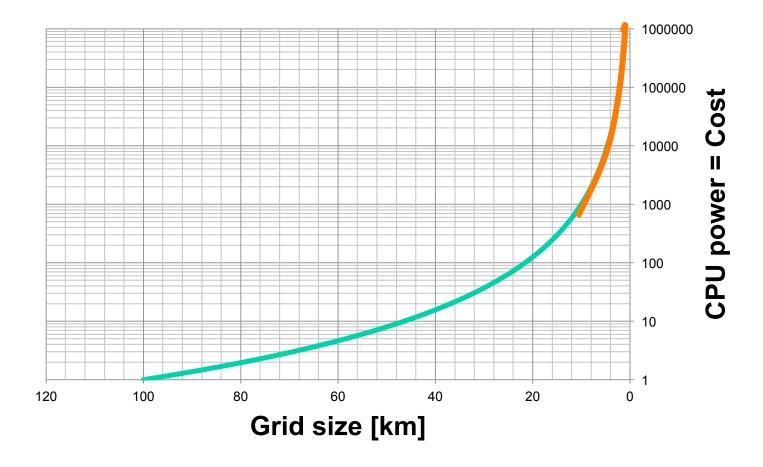


Medium resolution – 9 km





Why not always use 1km resolution? Atmos. and Meteorological Instrumentation – EGU 2012



Need 1000-times more CPU power to simulate a 1 km resolution forecast than a 10 km one for the same region!



What if

- You only need high very high resolution once in a while?
- Computer clouds (e.g. Azure, EC2 and GreenQloud) are starting to offer HPC service
- Offers great scalability
- Relatively cheap
- And there is already a solution out there ©

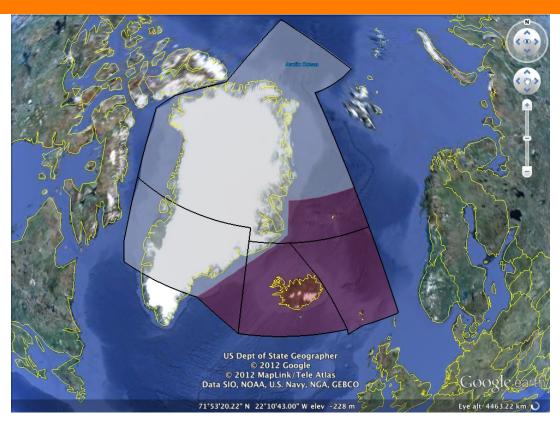


Routing optimization

- Recent M.Sc. project at the RU aimed at minimize fuel burn and emissions by optimizing flight tracks with respect to wind
- Used the Dijkstra search algorithm
- Used data from Icelandair
 - Keflavík New York flight @ 2011-07-14
 - Keflavík Copenhagen flight @ 2011-07-14
 - Boeing 757-200
- Fuel savings estimated using the BADA model



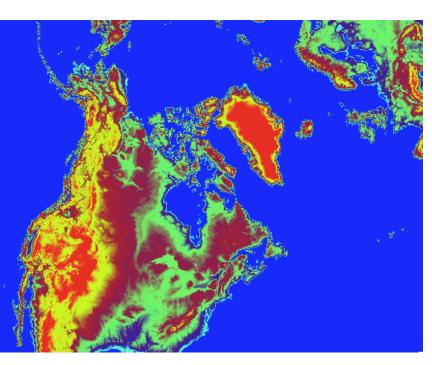
Reykjavík ATC area



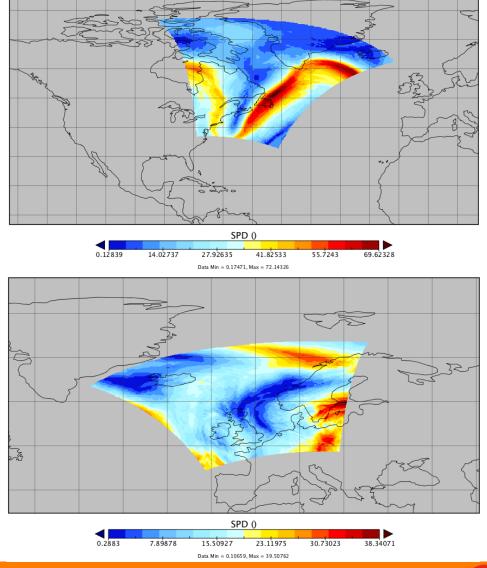
- Reykjavík Air Traffic Control area (BIRD)
- Over 110.000 flights in 2011
- Average time spend within BIRD was 100 minutes
- 1% fuel savings would amount to 6.000 metric tons



NWM area



- Weather was simulated over a large region @ 9km resolution
- Part of domain used to optimize the routes between Keflavík and New York and Keflavík and Copenhagen





Flight ICE615 – Keflavík New York

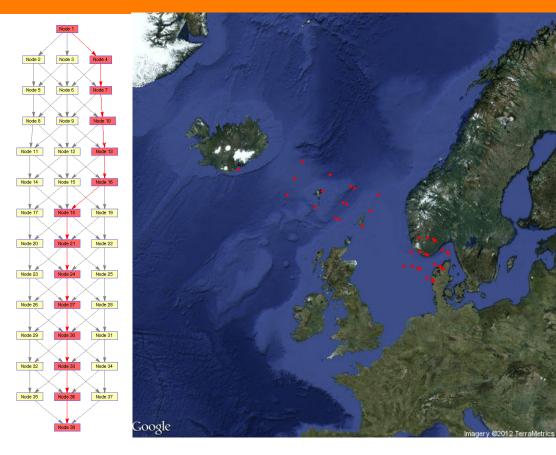


Flight	Dijkstra Path in	min Elight plan in min	Fuel saved in kg
ICE615	294.7	Node 53 Node 55 297	132



Flight ICE204 – Keflavík/Copenhagen

- Similar results found for another flight @
 2011-07-14
- Approximately 1% fuel savings for the whole flight
- Note that there was not "much" weather during this day
- Perhaps more to be gained in stronger winds?



Flight	Dijkstra Path in min	Flight plan in min	Fuel saved in kg
ICE204	123.3	124.5	66.8



Crisis Response System

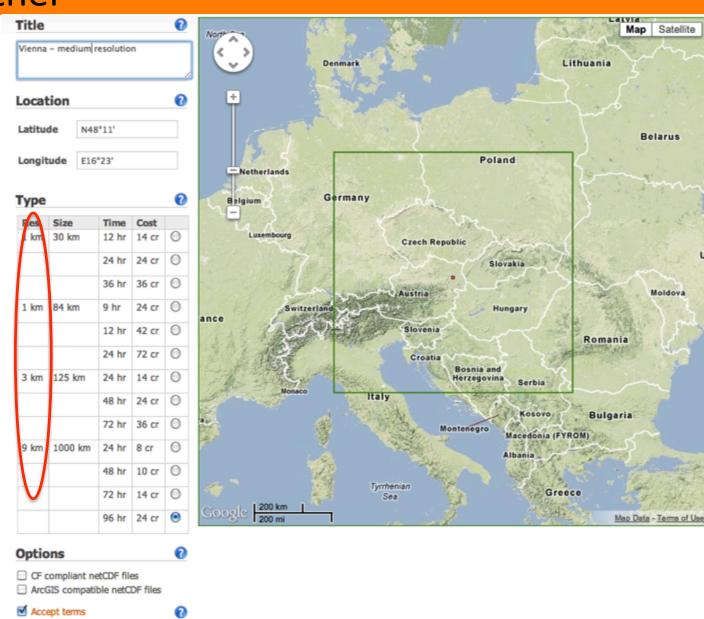
- Good weather information help improve decision making
- Current CRS uses the WRF model and consists of a
 - Backend and Frontend
- Frontend is called SARWeather
 - Easy to use
 - Fast
 - Flexible model output and presentation
 - CF and ArcGIS compliant output files
 - Interactive and static maps



Give the forecast a name

Type in Lat/Lon or click on the map

Choose resolution: 1, 3, or 9 km



Request Forecast

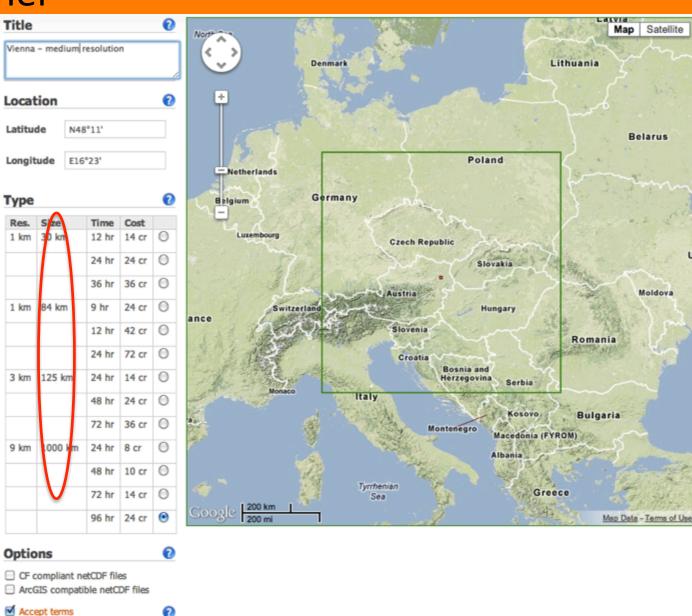




Give the forecast a name

Type in Lat/Lon or click on the map

Choose domain size



Request Forecast



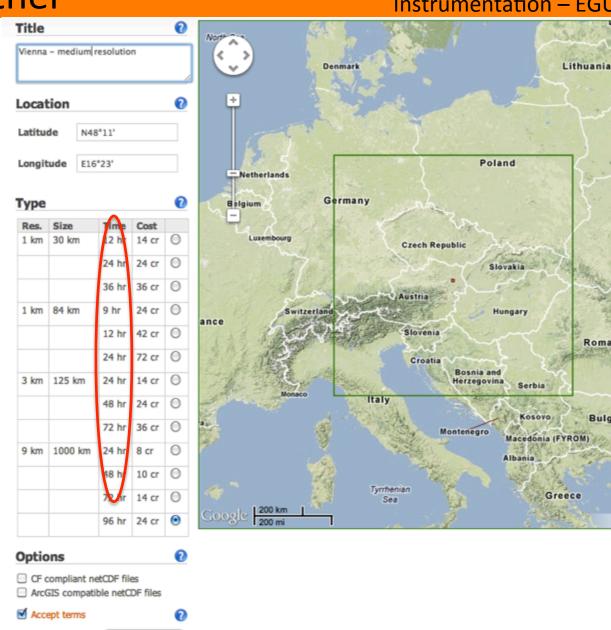


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Give the forecast a name

Type in Lat/Lon or click on the map

Choose forecast duration



Request Forecast



Map Data - Terms of Use

Map Satellite

Belarus

Moldova

Romania

Bulgaria

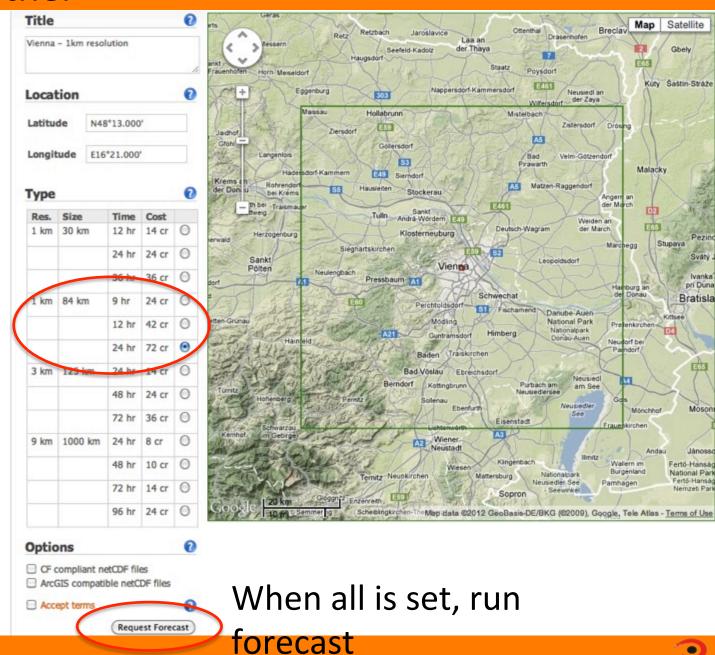
Give the forecast a name

Type in Lat/Lon or click on the map

1km resolution, 84x84 km domain and 24 hr forecast

Do you need CF or ArcGIS compliant output files?

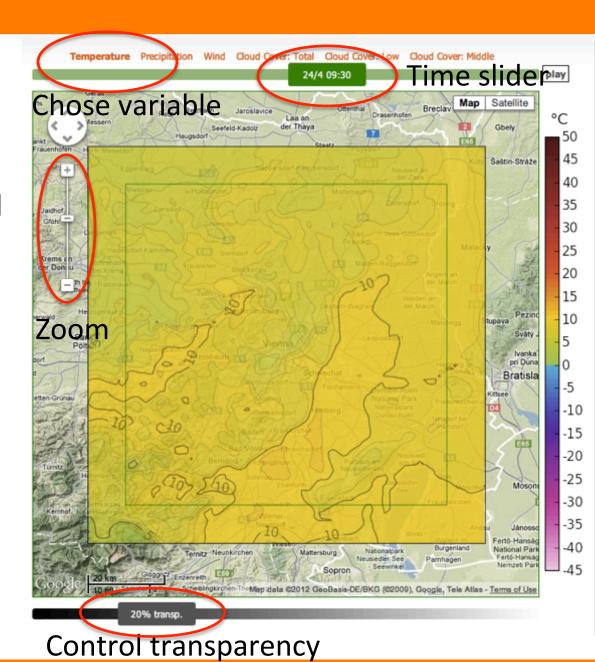
SARWeather



rannís

Time from initiation: 30 sec – computer node up'n running 2 min 40 sec – preprocessing done and model starts running 5 min 50 sec – first frame ready on screen 51 min 50 sec – 24 hr forecast ready 54 min 20 sec – "static" post-processing done

Typical response time for SAR operators is 30 min or less SARWeather





High resolution not always sufficient

Simulated and observed surface winds on 15 July 2009 at 13 UTC

21.5°W

64.5°N WRF at a resolution of 500 m forced with ECMWF-data on model levels. Mt. Esja Observed surface winds in red

Model simulates a see-breeze that is not seen in observations

m/s

SARWeather

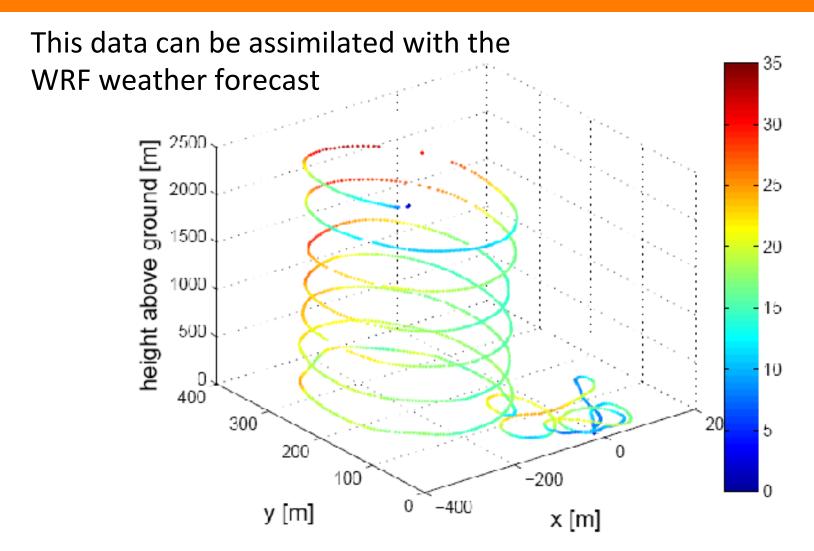
SUMO and WRF

The SUMO (Small Unmanned Meteorological Observer) can measure winds, humidity, pressure, and temperature in a vertical profile up to a 4km height





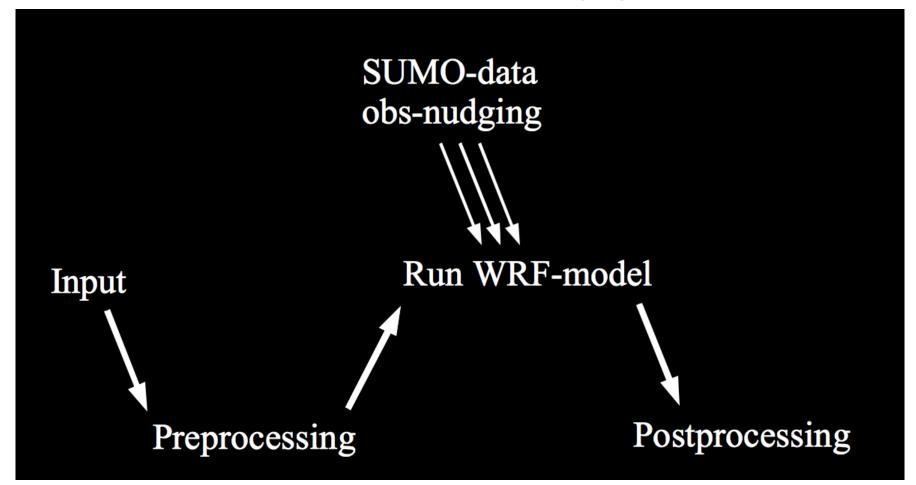
SUMO and WRF





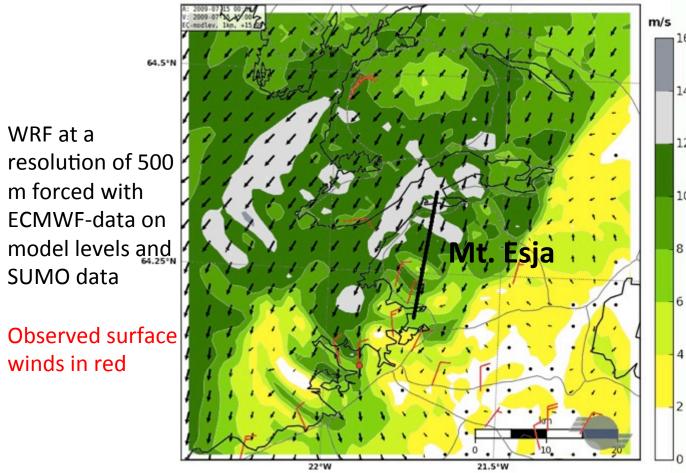
SUMO and WRF

The SUMO-data is incorporated into the WRF-simulation, via obs-nudging



Effects of additional observations

Simulated and observed surface winds on 15 July 2009 at 13 UTC

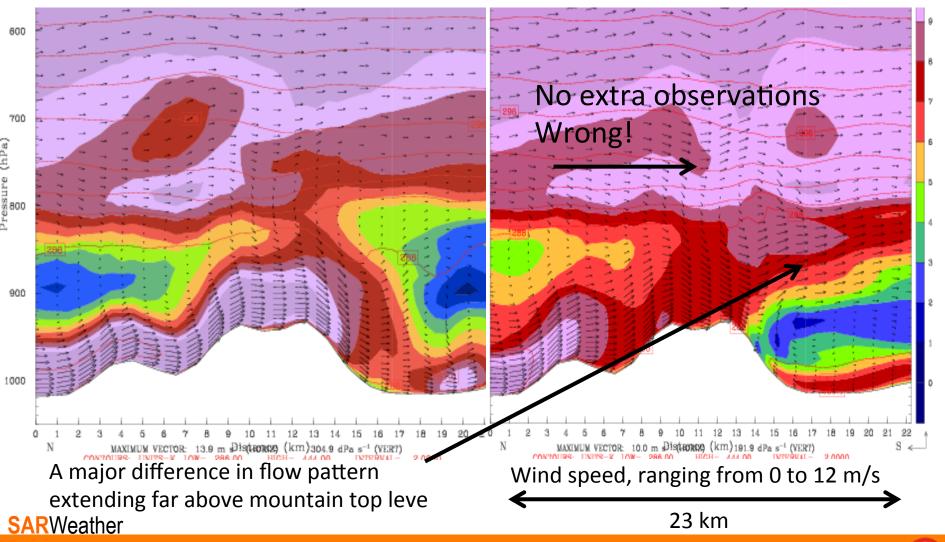


The flow structure

14 is now in much
12 better agreement
with available
observations

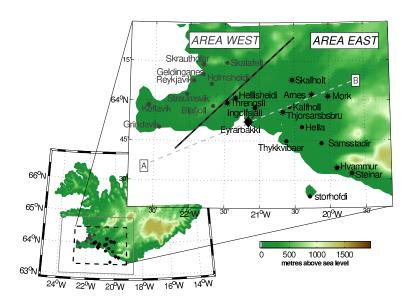
Effects not just at the surface

Simulated flow in N-S section across Mt. Esja



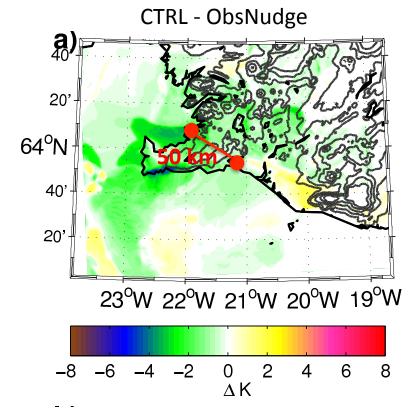


Effects can be far reaching



Marius O. Jonassen, Haraldur Ólafsson, Hálfdán Ágústsson, Ólafur Rögnvaldsson, and Joachim Reuder (2012). Improving a high resolution numerical weather simulation by assimilating data from an unmanned aerial system. Accepted for publication in *Monthly Weather Review*

"Substantial improvements of winds, temperatures and humidity in the region are achieved"







Additional sensors

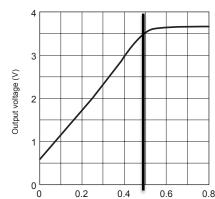
The SUMO has been equipped with an optical dust sensor Compact Optical Dust Sensor

GP2Y1010AU0F is a dust sensor by optical sensing system:

- An infrared emitting diode (IRED) and an phototransistor are diagonally arranged into the device
- It detects the reflected light of dust in air
- Especially effective to detect very fine particle
- In addition it can distinguish smoke from house dust by pulse pattern of output voltage



Output Voltage vs. Dust Density

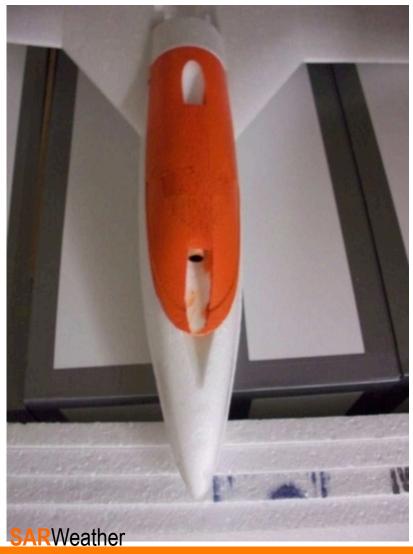


Saturation at about 500µg/m³



Preliminary results

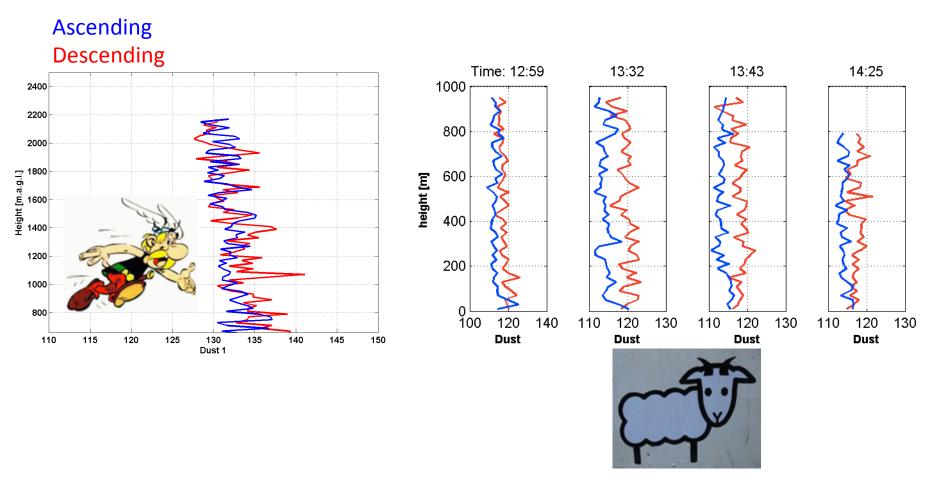
The SUMO dust sensor has been tested in France and Iceland





Preliminary results

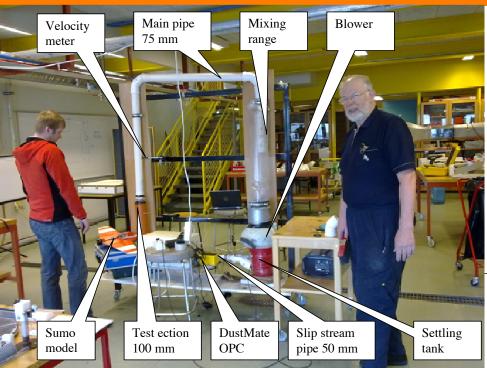
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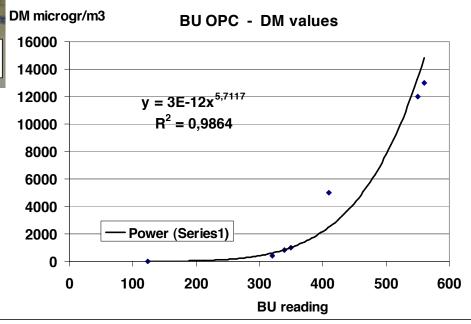
Sensor is now being calibrated and tested with ash from Mt. Eyjafjallajökull



Calibration – preliminary results



- The sensor (BU) readings show high sensitivity in the range 125 – 300.
 After that the sensitivity is rather low in the range 350 to 700.
- Using the meter for ash surveillance for jet aircrafts, the best thing would be to designate below 300 as "safe" but above 400 as "unsafe"

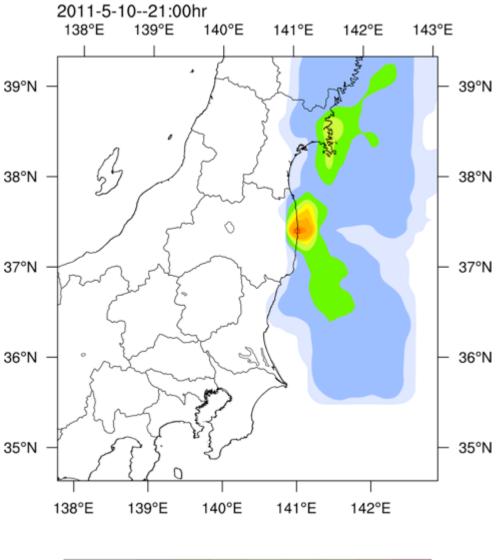






Various uses of model output

Dry Deposition (normalized by source conc) %



To correctly simulate
39°N distribution of pollutants, it is
very important to correctly
simulate the atmospheric
38°N conditions close to the source.

Data courtesy of Prof. Saji Hameed at the University of Aizu, Fukushima.



0.1

10

30

100

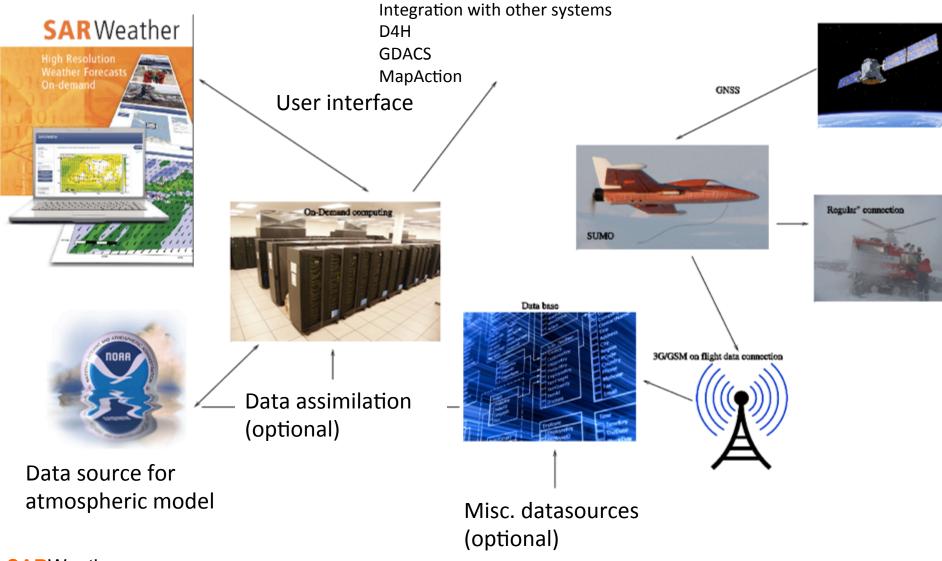
150

300

600

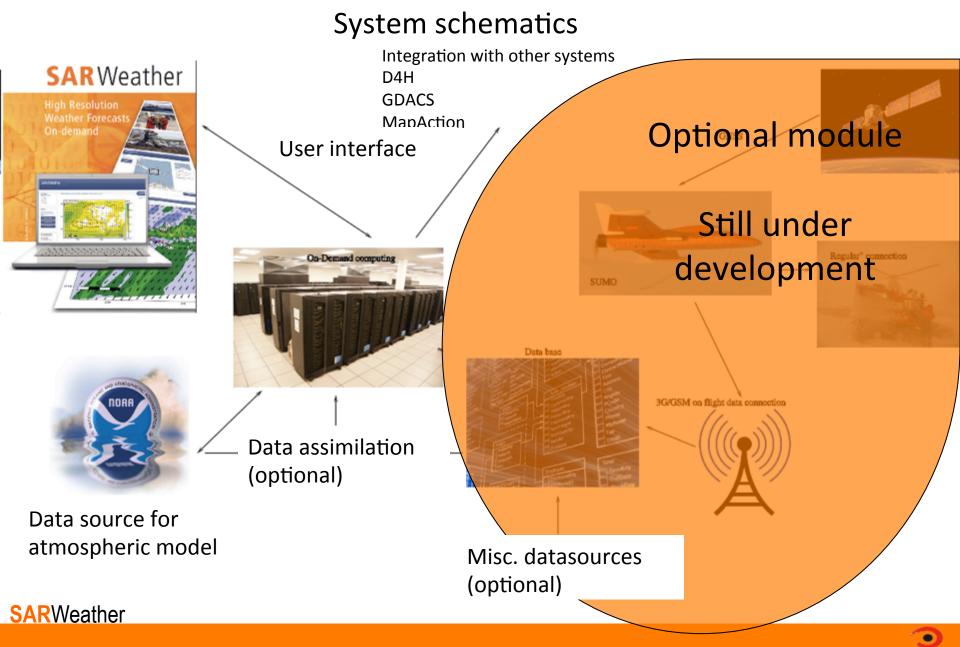
Current research and development

System schematics





Current research and development



Conclusions

- Model resolution is important
 - Especially in the vicinity of complex terrain
- Additional observations can improve the simulation
 - Vertical profiles made by the SUMO
- The SUMO is a low-cost system with many advantages
 - Proof of concept before investing in a more durable and expensive UAS
 - Additional sensors are being added to the system
- Fast response time is crucial in SAR operations
 - SARWeather meets these needs
 - Good weather information help improve decisions
- The SUMO is currently being integrated to the SARWeather, on-demand, Crisis Response System



Acknowledgement

- SARWeather is a joint research project led by IMR/Belgingur, in collaboration with NOAA/ESRL, the University of Bergen, and the private companies GreenQloud and DataMarket. To ensure maximum usability for SAR operators, SARWeather is developed in close collaboration with ICE-SAR and the Civil Protection Department of the Icelandic Police.
- SARWeather was initially funded in part by grant number 550-025
 (Vejrtjeneste for Søberedskab) from NORA and by the European
 Commission under the 7th Community Framework Programme for
 Research and Technological Development (GalileoCast). GalileoCast is
 managed by GSA, the European GNSS Supervisory Authority.
- Current development of SARWeather is funded in part by the Icelandic Technical Development Fund – RANNÍS
- Development related to the SUMO has in part been funded by the COST project ES0802

